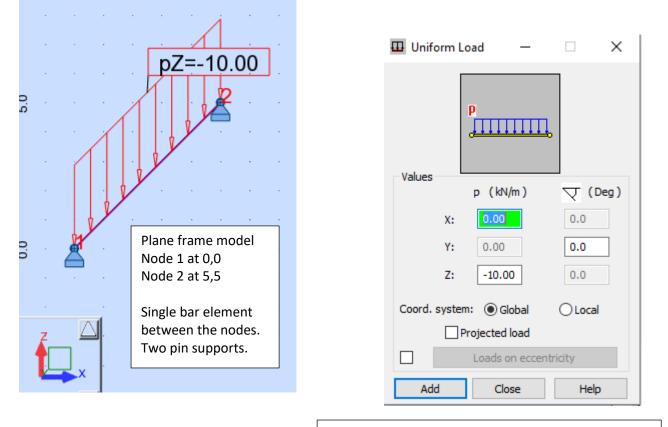
# **Guidance for Robot**

#### Loads on sloping members

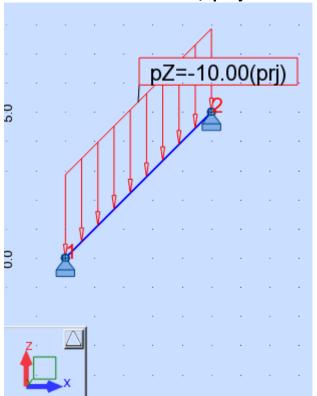


#### 1. Global Z direction load, not projected

Load definition for a bar element . **Global** selected means that the load will be applied in the global direction (Z in this case). With the **Projected Load** box not ticked, the load will be per unit along the length of the member which in this case is 7.74m Therefore the total load is 10\*7.74 = 77.4 kN

Node/Case	FX (kN)	FZ (kN)	MY (kNm)
1/ 1	0.0	38.70	0.0
2/ 1	0.0	38.70	0.0
Case 1	LL1		
Sum of val.	0.0	77.41	0.0
Sum of reac.	0.0	77.41	-193.52
Sum of forc.	0.0	-77.41	193.52
Check val.	0.0	0.0	0.0
Precision	0.0	0.0	

**Results for reactions** 



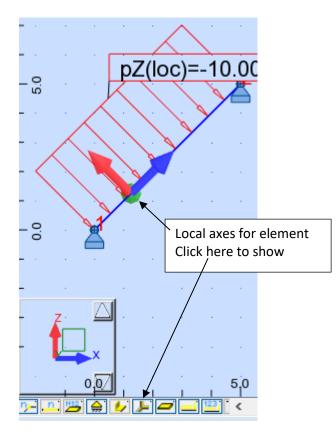
#### 🛄 Uniform Load $\times$ Values p (kN/m) 文 (Deg) 0.00 0.0 X: Y: 0.00 0.0 Z: -10.00 0.0 Coord. system: Global OLocal Projected load Loads on eccentricity Add Close Help

With the **Projected Load** box ticked, the load will be per unit along the length of the Z projection of the member i.e. along a length of 5m. Therefore the total load is 10\*5 = 50 kN

Node/Case	FX (kN)	FZ (kN)	MY (kNm)	
1/ 1	-0.00	25.00	0.0	
2/ 1	0.00	25.00	-0.00	
				Results for reactions
Case 1	LL1			
Sum of val.	0.0	50.00	-0.00	
Sum of reac.	0.0	50.00	-125.00	
Sum of forc.	0.0	-50.00	125.00	
Check val.	0.0	0.0	0.0	
Precision	6.98492e-16	0.0		

### 2. Global Z direction load, projected

### 3. Local Z direction load



🖽 Uniform Lo	ad	_		$\times$
Values	₽ 	<u></u>		
Values	p (kN	/m )	고 (I	Deg )
х:	0.00		0.0	
Y:	0.00		0.0	
Z:	-10.0	0	0.0	
Coord. system	ii O Gla		Local	I
	Loads o	n eccentri	icity	
Add	Clo	se	Help	<b>)</b>

With the **Local Load** box ticked, the load will be in the local Z direction as shown. The reactions are shown in the table.

Node/Case	FX (kN)	FZ (kN)	MY (kNm)	
1/ 1	-25.00	25.00	0.00	
2/ 1	-25.00	25.00	-0.00	
Case 1	LL1			Results for reactions in globa
Sum of val.	-50.00	50.00	0.0	coordinates
Sum of reac.	-50.00	50.00	-250.00	coordinates
Sum of forc.	50.00	-50.00	250.00	
Check val.	0.0	0.0	0.0	
Precision	1.74623e-16	0.0		

## Setting the number of significant digits for numbers in a table

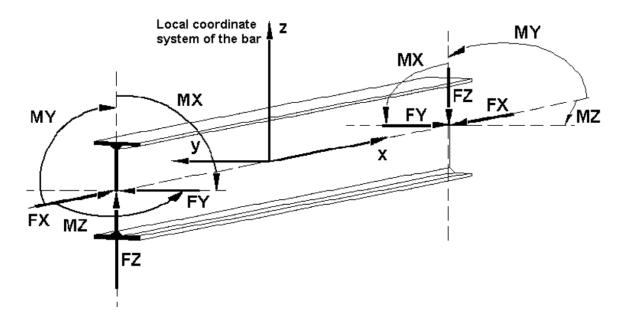
Right click on a table and select 'Units and Formats' from the menu. This brings up the dialog box as shown below. The number of significant digits can be increased up to 9 in Robot. In the example below the number of significant digits is set at the maximum of 9 for forces and for moments. In structural engineering calculations output values seldom are to better than 2 or 3 digit accuracy and should not be quoted to a greater number of digits than is appropriate.

It is only when considering the *numerical* significance of numbers that more digits should be used. This occurs when doing equilibrium and symmetry checks.

Bar/Node/Case	FX (kN)	FZ (kN)	MY (kNm)			
1/ 1/ 1	0.0	35.355339059	0.000000000			
1/2/1	0.0	-35.355339059	0.000000000			
Job Preferences					?	×
😅 🖶 🗙 关	DEFAULTS	5				$\sim$
Units and Formats Units and Formats Forces Other Unit Edition Materials  Databases Codes Structure Analysis Work Parameters Meshing	Mc	rce: oment: resses:	kN kN*m MN/m2	<ul> <li>0.987654321</li> <li></li> <li>0.987654321</li> <li></li> <li>0.21</li> </ul>	<ul> <li>• • E</li> <li>• • E</li> </ul>	
🙀 Open	default param	eters				
🖳 <u>S</u> ave curre	ent parameters	as default		OK Cancel	Help	

# Sign convention for internal force actions in beam elements

Positive directions of forces and moments:



#### Notes:

- 1. Compression is positive
- 2. The positive directions of the My moments gives tension on the underside of a horizontal beam . Threfore when a bending moment diagram is drawn for My moments, they are on the side of the beam that is in tension. This is the normal convention in structural engineering because it shows the side of the beam for tension reinforcement in reinforced concrete.

